

INSTRUCTION MANUAL

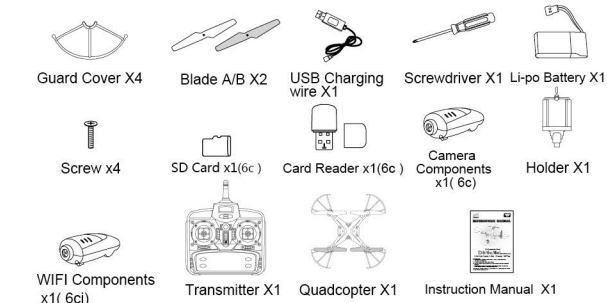
AGES 14+



R/c Quadcopter Series
D6/6c/6ci General Instructions
 6-Axis Gyro System 2.4Ghz 5Channel 360°Flips

- Main Functions:**
- Common Mode: High/Low Speed, Micron Tuning, Forward, Backward, Left, right, Turn Left/Right.
 - 3D Mode: Rotate 360°, Back Home Button.
 - Headless Mode: it allows to fly forwards, backwards, left and right regardless of angles.
 - Optional Parts: remote control camera, high definition camera components, or WIFI image real-time transmission components.
- This manual is suitable for Item D6, D6c and D6ci. The functions not suitable for all, will be remarked as a note.

1 INCLUDED PARTS



2 TRANSMITTER

2.1 Introduction of transmitter

Left lever(Ascend / descend /Left/right turn)Press down to Headless mode

Right lever (Forward/backward Left/right sideward fly) Press down to 3D flip

fast slow gear

Power switch

Return button

Light control

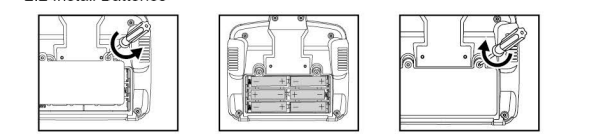
Power Indicator

Right lever (Forward/backward Left/right sideward fly) Press down to 3D flip

Trimming Start button

Photo button (Need to buy Camera Components)

Video button (Need to buy Camera Components)



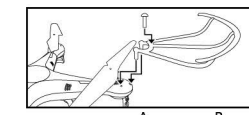
- 2.2 Install Batteries**
- Make sure the polarity of the battery and battery box should be correct and can't be loaded upside down.
 - Please do not mix using the old batteries with the new ones.
 - Please do not mix using batteries with different types.

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3 INCLUDED PARTS

3.1 Mount Guard Cover
 Push the guard cover into the motor base, and fasten it with a nut. Important Notice: It is strongly recommended to mount the guard cover before playing the quadcopter to avoid any potential damages.

3.2 Mount/Change Blades
 Each blade must mount to designated location. Blade A shall be mounted to Location A, while Blade B to Location B as shown on the diagram. Improper mounted blades may cause problems, such as taking-off failure, deviation or crashing down.



Blade installation diagram

4 CHARGING LI-PO BATTERY

Switch off the quadcopter, take off the battery compartment cover, take out the battery connector and connect it to USB to charge. The indicator will light on during charging and light off once charging is complete. Then connect the battery to the quadcopter as shown on Diagrams ready to fly.



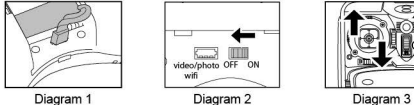
Charging time: About 100 minutes; Flight time: More than 6 minutes

- please pay attention to the following security matters.
- Do not put the rechargeable batteries in the place of high temperature, such as fire, electric heating device, or it may cause damage and explode.
 - Do not strike the batteries
 - Do not put the batteries into the water, the batteries should be kept in a dry place.
 - Do not decompose the batteries.
 - Do not leave when you are charging

5 STANDBY FOR FLY

5.1 Operation System Booting

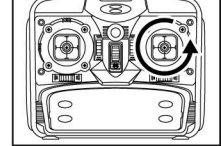
5.1.1
 Diagram 1: Connect the battery to the quadcopter.
 Diagram 2: Switch on the flying object and put it on the ground.
 Diagram 3: The LED indicators will flash to pair the flying object with the controller. Switch on the controller to pair. The indicators will light on instead of flashing when pairing is complete. Push the left lever /accelerator to top with a beep, then pull down to bottom with a beep to unlock.



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5.2 Calibration

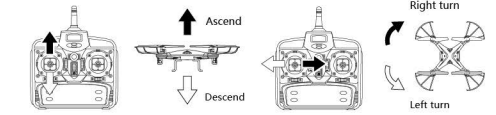
After pairing, place turn the right lever a round counterclockwise. Four lights on the quadcopter flash. The calibration finishes.
 Note: The quadcopter has been well calibrated before delivery. It is not necessary to recalibrate without need.



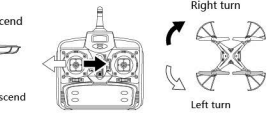
6 OPERATING AND CONTROL

6.1 Operating Instructions

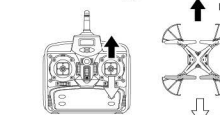
If the quadcopter falls down in showing, the operator can accelerate slowly to have the quadcopter going up as needed. Caution: the acceleration shall be very gentle, or it may cause damage out of control.



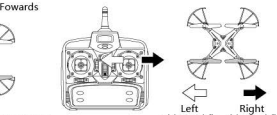
Push the left lever (accelerator)up and down, The quadcopter will ascend and descends accordingly.



Push the left lever (accelerator)leftward and rightward,the quadcopter will turn left and turn right accordingly.



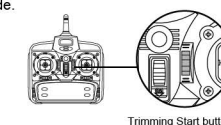
Push the right lever (swerving rudder) , the quadcopter will go forward and backward accordingly.



Push the right lever (swerving rudder) leftward and rightward, the quadcopter will go leftward and rightward accordingly.

6.2 Trimming

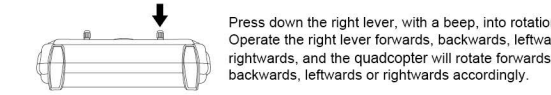
Press down the micro tuning button into micro-tuning mode.
 ※If the quadcopter deviates forwards, the operator shall pull the right rod backwards to adjust with the rear two indicators flashing.
 ※If the quadcopter deviates backwards, the operator shall pull the right rod forwards to adjust with the front two indicators flashing.
 ※If the quadcopter deviates leftwards, the operator shall pull the right rod rightwards to adjust with the right two indicators flashing.



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※If the quadcopter deviates rightwards, the operator shall pull the right lever leftwards to adjust with the left two indicators flashing. The tuning can be made repeatedly till it flies steadily. Then press down the tuning button to exit.Please kindly note that the tuning mode will exit automatically if no operation within 3 seconds.

7 3D Flips Mode



Press down the right lever, with a beep, into rotation mode. Operate the right lever forwards, backwards, leftwards or rightwards, and the quadcopter will rotate forwards, backwards, leftwards or rightwards accordingly.

It is strongly recommended that the rotation shall be made by keeping the quadcopter with a certain height, such as 1.2 meters high, and keeping it in hovering, avoid any potential damage.

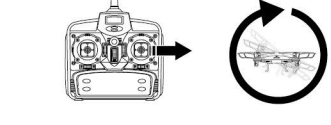
7.1 Leftward flip

Press down the right lever , with a beep, push the lever leftward, the quadcopter will flip one circle leftward.



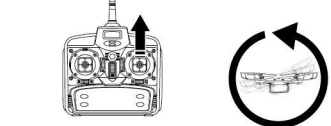
7.2 Rightward flip

Press down the right lever , with a beep, push the lever rightward, the quadcopter will flip one circle rightward.



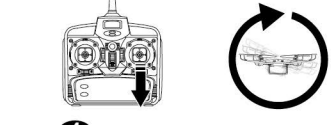
7.3 Forward flip

Press down the right lever ,with a beep,push the lever forward, the quadcopter will flip one circle forward.



7.4 Backward flip

Press down the right lever , with a beep,pull the lever backward, the quadcopter will flip one circle backward.

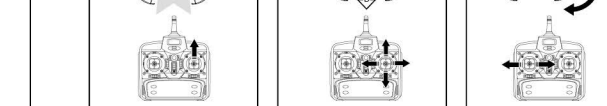
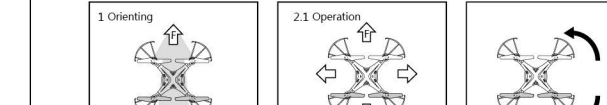
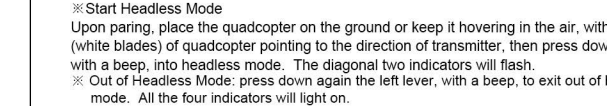


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Low Battery Alarm
 When all the four indicators flash at the same time, it is a signal of low battery. The rotation function will be closed automatically.

8 Headless Mode

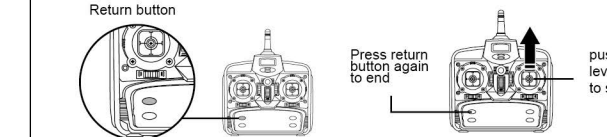
8.1 Mode Change
 With new remote control skill and automatic identification, you can call back the quadcopter no matter where it is.
 ※Start Headless Mode
 Upon paring, place the quadcopter on the ground or keep it hovering in the air, with the head (white blades) of quadcopter pointing to the direction of transmitter, then press down left lever, with a beep, into headless mode. The diagonal two indicators will flash.
 ※ Out of Headless Mode: press down again the left lever, with a beep, to exit out of headless mode. All the four indicators will light on.



As shown on diagrams, in headless mode, no matter which direction the quadcopter pointing, the operator can call it back by pulling down the right lever, and fly it far away by pushing the right rod up.

8.2 Return

Return : In headless mode, press down the Return button on the transmitter (diagram 1). The quadcopter will automatically return.If the quadcopter off course,when return. Please control the right lever fixed route, press down the return button or push the right lever "forward" let the quadcopter stop return(diagram 2).



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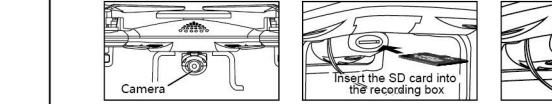
9 CAMERA FUNCTION (D6c)

9.1 Mount Camera and WIFI Components (D6c/ D6ci)



Mount the camera onto the bottom of quadcopter by inserting it into the battery compartment.

Connect the cable of camera into the socket.



9.2 Mount SD Card
 Insert SD card into the slot, press down to insert and press down again to pop up. Please note that the red and green indicators under the camera will flash alternately to remind to insert SD card.

9.3 CAM/VIDEO Function
 Switch on the quadcopter, press down the CAM/VIDEO button on the controller into camera or video mode. Each shot will have the red indicator flash one time; video recording will trigger the red indicator flashing all the time till finishing recording. The pictures or videos will be stored in SD card.

9.4 Video/Picture Treatment
 Switch off the flying object to take out SD card. Put SD card into a card reader to browse or download the videos or pictures.

10. WIFI Transmission in Real Time (D6ci)

10.1 Mount the Holder of Cell Phone (D6ci)



Mount the holder of cell phone to the top of the controller.

The holder is flexible to suit different phones.

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10.2 Software Download



ios QR Code

Android QR Code

10.3 Switch on the flying object, open WIFI on the phone. Find the option of WIFI "FPV-*****" on the WIFI list and connect till it shows Connected. Open the application of Skyline on the phone into control panel. The phone will display the real time screen on the camera.

11 FLIGHT ENVIRONMENT:



Under the bad conditions above, the quadcopter shall not operate to avoid any potential damages.

12 TROUBLE SHOOTING

- 12.1 Transmitter and quadcopter not bland solution:**Make sure Frequency of success.
- 12.2 Gyro not working well:**
 Solution: 1)Battery voltage too low.
 2)Re-bind.
 3)Make sure the quadcopter on the horizontal position.
- 12.3 Unable to flip**
 Solution: 1)Press right lever ,change to flip mode.
 2)Check if li-po power is too low and needs to be recharged.
- 12.4 Quadcopter is shaking with noise:**
 Solution: Check if the motors, canopy,body and propellers are all properly positioned.
- 12.5 Cannot take off.**
 Solution: 1)Wrong installation of the props. All props are marked with "A" or "B" and should be placed on the right motor (marked "A" or "B")respectively for the correct order
 2)Check quadcopter canopy if loose or not,block blades flying
 3)Check quadcopter battery is power full,if the low power, quadcopter canopy inner light will be alternately flashing.

Caution: The flying object may have potential hazards to children. A child must have adult's monitoring and assistance.

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